1. 12 points What is the big-O time complexity of the following flood method in terms of the total number of tiles, represented by n? Provide an argument for your answer that analyzes every statement in the method and how their individual time complexities combine into the total time complexity.

2. 10 points Complete the following implementation of the Counting Sort algorithm by filling in the blanks.

```
static void counting_sort(int[] A, int[] B, int k) {
    int[] C = new int[k];
    int[] L = new int[k];
    for (int i = 0; i != A.length; ++i) {
        C[____(a)___] += 1;
    }
    L[0] = ____(b)____;
    for (int j = 1; j != k; ++j) {
            L[j] = C[j] + ____(c)___;
    }
    for (int j = A.length - 1; j != -1; --j) {
            B[____(d)___] = A[j];
            L[____(e)___] -= 1;
    }
}
```

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3. 8 points Given the following definition of function g, what is the result of g(2, 1)? Show your work by listing the arguments and the return value for each call to g.

```
public static int g(int m, int n) {
    if (n == 0)
        return m + 2;
    else if (m == 0)
        return g(1, n-1);
    else
        return g(g(n-1, n), n-1);
}
```

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^{4. 8} points Apply the Partition algorithm to the following array, ensuring that all elements less or equal to the pivot element are in lower positions and all elements greater than the pivot are in greater positions. The pivot element starts out as the last element of the array. Write down the initial array and the array after each step (each iteration of the loop), drawing two vertical lines to separate the three partitions (the less-than or equal region, the greater-than region, and the to-do region).

 $\left[8,2,7,3,5\right]$

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5. 10 points Show that $4n \log n + 10 \leq n^2$ using the definition of asymptotic less-or-equal (aka. big-O).

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6. 10 points For the following Node class in a binary tree, fill in the blanks to complete the **previous** method that returns the node that comes before the current node with respect to an inorder traversal, if there is one, and **null** if there is none.

```
class Node {
    T data;
    Node left, right, parent;
    public Node previous() {
        if (left == null) {
            return ___(a)___;
        } else {
            return ___(b)___;
        }
    }
    public Node last() {
        if (right == null)
            return this;
        else
            return ___(c)__;
    }
    public Node prevAncestor() {
        Node q = this;
        Node p = q.parent;
        while (p != null && ___(d)___) {
            q = p;
            p = ____(e)____;
        }
        return p;
    }
}
```

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7. 10 points Given the following definitions of the sum and rev_app functions, prove the sum_rev_app theorem specified below. The proof can be carefully written in English or in the Deduce language.

```
function sum(List<Nat>) -> Nat {
  sum(empty) = 0
  sum(node(x, xs)) = x + sum(xs)
}
function rev_app<T>(List<T>, List<T>) -> List<T> {
  rev_app(empty, ys) = ys
  rev_app(node(x, xs), ys) = rev_app(xs, node(x, ys))
}
theorem sum_rev_app: all xs : List<Nat>. all ys:List<Nat>.
  sum(rev_app(xs, ys)) = sum(xs) + sum(ys)
```

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8. 8 points Which of the following are valid tests for the find_first_true function? A valid test is one that satisfies the preconditions of find_first_true and that checks for the correct result. For each of the five tests below, write "valid" or "invalid" next to it. Recall the specification for find_first_true:

Specification: The find_first_true(A, begin, end) function returns the smallest index i in the half-open range specified by begin and end such that A[i] is true. If there are no true elements in the range, then find_first_true returns the end position. The caller of find_first_true is required to provide a valid half-open range for array A, which means begin <= end, 0 <= begin, begin <= A.length, 0 <= end, and end <= A.length.

```
1. boolean[] A = {true, false};
assertEquals(0, Search.find_first_true(A, 1, 0));
```

- 2. boolean[] A = {true, false, true}; assertEquals(2, Search.find_first_true(A, 1, 3));
- 3. boolean[] A = {false, false, false}; assertEquals(2, Search.find_first_true(A,0,2));
- 4. boolean[] A = {true, true, false};
 assertEquals(1, Search.find_first_true(A, 0, 3));

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9. 10 points Implement a generic version of the Quicksort Algorithm that sorts a halfopen range of elements, given by a pair of iterators. Recall the following definition of the Iterator interface. You do not need to implement the partition helper function.

```
interface Iterator<T> {
    T get();
    void set(T e);
    void advance();
    boolean equals(Iterator<T> other);
    Iterator<T> clone();
}
static <E extends Comparable<? super E>>
Iterator<E> partition(Iterator<E> begin, Iterator<E> end);
static <E extends Comparable<? super E>>
void quicksort(Iterator<E> begin, Iterator<E> end) {
```

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10. 8 points What are the big-O time complexities for the get and contains methods of the Java LinkedList class?

What are the big-O time complexities for the get and contains methods of the Java ArrayList class?

11. 6 points What is the big-O time complexity of the following insertion_sort function? Explain your answer in detail, giving the big-O for the insert and isort helper functions. You may assume that the <= operator is O(1).

```
function insert(List<Nat>,Nat) -> List<Nat> {
    insert(empty, x) = node(x, empty)
    insert(node(y, next), x) =
        if x <= y then
            node(x, node(y, next))
        else
            node(y, insert(next, x))
    }
function isort(List<Nat>, List<Nat>) -> List<Nat> {
        isort(empty, ys) = ys
        isort(node(x, xs), ys) = isort(xs, insert(ys, x))
    }
define insertion_sort : fn List<Nat> -> List<Nat>
        = fun xs{ isort(xs, empty) }
```